Hands-on – The Hello World! Program
Class Objectives

- You will learn how to write, build and run “Hello World!” on the Cell System Simulator
- Navigate through the basic build process and make files
- Familiarize with gcc and xlc compilers
- Familiarize with the system simulator
- There are three different versions of “Hello World!” used in this session
  - PPE only,
  - SPE only, and
  - Cell BE, i.e. using both PPE and SPE
    - Synchronous
    - Asynchronous

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How to build, compile and execute the “Hello World!” program

- **Pre-requisites**
  - Toolchain
  - Compiler

- **Build Process**

- **Source Code**
  - Makefiles
  - Source PPE
  - Source SPE

- **Simulator**
  - Getting the binary into the simulator
  - Running the binary
The build process
Build Process
SDK 3.0 Makefile
Compiling within the SDK

- **Top of build environment is /opt/cell/sdk/**

- **Includes the build environment files**
  - README_build_env.txt
    - Provides details on the build environment features, including files, structure and variables.
  - make.footer
    - Specifies all of the build rules needed to properly build CBEA binaries
    - Must be included in all SDK Makefiles (referenced relatively if $CELL_TOP is not defined)
    - Includes make.header
  - make.header
    - Specifies definitions needed to process the Makefiles
    - Includes make.env
  - make.env
    - Specifies the default compilers and tools to be used by make

- **make.footer and make.header should not be modified**
Common Makefile variables

- **DIRS**
  - list of subdirectories to build first

- **PROGRAM_ppu**
  - 32-bit PPU program (or list of programs) to build.

- **PROGRAM_ppu64**
  - 64-bit PPU program (or list of programs) to build.

- **PROGRAM_spu**
  - SPU program (or list of programs) to build.
  - If written as a standalone binary, can run without being embedded in a PPU program.

- **LIBRARY_embed**
  - Creates a linked library from an SPU program to be embedded into a 32-bit or 64-bit PPU program.

- **OBJJS**
  - List of objects for the programs (or one specific program). By default, all objects in the current directory are linked into the binary.

- **IMPORTS**
  - List of libraries to link in the programs (or one specific program). Also used by the PPU programs to embed the SPU linked library.
Directory Layout and Examples of Makefile

- **sample**
  - sample.h
  - Makefile
    - DIRS = spu ppu
    - include $(CELL_TOP)/buildutils/make.footer

- **sample/spu**
  - Makefile
    - sample_spu.c
    - PROGRAM_spu = sample_spu
    - LIBRARY_embed = lib_sample_spu.a
    - include $(CELL_TOP)/buildutils/make.footer

- **sample/ppu**
  - Makefile
    - sample.c
    - PROGRAM_ppu = sample
    - IMPORTS = ../spu/lib_sample_spu.a
    - include $(CELL_TOP)/buildutils/make.footer
Building The Code

- **Environment setup**
  - Set the CELL_TOP environment variable so that the makefile system can be found:
    - export CELL_TOP=/opt/cell/sdk/
    - make.footer contains the build rules for the makefile system
  - Ensure compilers or cross-compilers are in the executable search path

- **Separate SPE code and PPE code into different directories**
  - Each set of code has its own makefile and toolchain to use
  - Suggestion: create a subdirectory called ‘spu’ in the directory where the PPU code is found

- **Makefile template for PPE code:**
  ```
  DIRS = spu
  PROGRAM_ppu = <PPU_executable_name>
  IMPORTS = <spu_executable-embed.a> -lspe2
  include $(CELL_TOP)/buildutils/make.footer
  ```

- **Makefile template for SPE code:**
  ```
  PROGRAM_spu = <SPU_executable_name>
  LIBRARY_embed = <spu_executable-embed.a>
  include $(CELL_TOP)/buildutils/make.footer
  ```
The “Hello World!” program
Four Different Versions of “Hello World!”

- **PPE only**
- **SPE only**
- **Synergistic PPE and SPE: synchronous**
  - One SPE is used.
  - Main thread blocks and waits for the SPE code to run to completion
- **Synergistic PPE and SPE: asynchronous**
  - Eight SPEs are used
  - Main thread uses pthreads to get concurrent/asynchronous execution
“Hello World!” – PPE Only

- **PPU program**
  - just like any “Hello World!” program one would write

```c
#include <stdio.h>

int main(void)
{
    printf("Hello world!\n");
    return 0;
}
```

- **Makefile**
  - make.footer included to set up compiler and compiler flags
  - PROGRAM_ppu tells make to use PPC cross-compiler

```
PROGRAM_ppu = hello_ppu
include $(CELL_TOP)/buildutils/make.footer
```

PROGRAM_ppu tells make to use PPC compiler
“Hello World!” – SPE Only

- **SPU Program**

```c
#include <stdio.h>

int main()
{
    printf("Hello world!\n");
    return 0;
}
```

- **SPU Makefile**

```makefile
PROGRAM_spu := hello_spu
include $(CELL_TOP)/buildutils/make.footer
```

PROGRAM_spu tells make to use SPE compiler
Synergistic PPE and SPE (SPE Embedded)

- Applications use software constructs called SPE contexts to manage and control SPEs.
- Linux schedules SPE contexts from all running applications onto the physical SPE resources in the system for execution according to the scheduling priorities and policies associated with the runnable SPE contexts.
- libspe provides the means for communication and data transfer between PPE threads and SPEs.
How does a PPE program start an SPE thread?

- 4 basic steps must be done by the PPE program
  - Create an SPE context.
  - Load an SPE executable object into the SPE context local store.
  - Run the SPE context. This transfers control to the operating system, which requests the actual scheduling of the context onto a physical SPE in the system.
  - Destroy the SPE context.
SPE context creation

- **spe_context_create** - Create and initialize a new SPE context data structure.

  ```c
  #include <libspe2.h>
  spe_context_ptr_t spe_context_create(unsigned int flags, spe_gang_context_ptr_t gang)
  ```

  - **flags** - A bit-wise OR of modifiers that are applied when the SPE context is created.
  - **gang** - Associate the new SPE context with this gang context. If NULL is specified, the new SPE context is not associated with any gang.
  - On success, a pointer to the newly created SPE context is returned.
spe_program_load

- **spe_program_load** - Load an SPE main program.

```c
#include <libspe2.h>

int spe_program_load (spe_context_ptr_t spe,
                      spe_program_handle_t *program)
```

- *spe* - A valid pointer to the SPE context for which an SPE program should be loaded.
- *program* - A valid address of a mapped SPE program.
**spe_context_run**

- **spe_context_run** - Request execution of an SPE context.

```c
#include <libspe2.h>

int spe_context_run(spe_context_ptr_t spe, unsigned int *entry, unsigned int runflags, void *argp, void *envp, spe_stop_info_t *stopinfo)
```

- `spe` - A pointer to the SPE context that should be run.
- `entry` - Input: The entry point, that is, the initial value of the SPU instruction pointer, at which the SPE program should start executing. If the value of entry is SPE_DEFAULT_ENTRY, the entry point for the SPU main program is obtained from the loaded SPE image. This is usually the local store address of the initialization function crt0.
- `runflags` - A bit mask that can be used to request certain specific behavior for the execution of the SPE context. 0 indicates default behavior.
- `argp` - An (optional) pointer to application specific data, and is passed as the second parameter to the SPE program,
- `envp` - An (optional) pointer to environment specific data, and is passed as the third parameter to the SPE program,
- `stopinfo` An (optional) pointer to a structure of type `spe_stop_info_t`
**spe_context_destroy**

- **spe_context_destroy** - Destroy the specified SPE context.
  
  ```c
  #include <libspe2.h>
  int spe_context_destroy (spe_context_ptr_t spe)
  ```

  - **spec** - Specifies the SPE context to be destroyed
  - On success, 0 (zero) is returned, else -1 is returned
“Hello World!” – PPE and SPE Combined Structure

- **SPU code**
  - Compiled with SPU specific toolchain
  - Object is repackaged as PPC ELF object
  - From this point forward normal PPU tools are used.

- **PPU code**
  - Compiled with normal PPU toolchain

- **Objects are linked to form a combined executable.**

- **At runtime, kernel extensions and SDK libraries are used to move the SPU code to an SPU and start the SPU thread.**
“Hello World!” – Synergistic PPE and SPE (SPE Embedded)

- **SPU program**
  - Same as for SPE only

- **SPU Makefile**

```makefile
PROGRAM_spu := hello_spu
LIBRARY_embed := hello_spu.a
include $(CELL_TOP)/buildutils/make.footer
```
“Hello World!” – PPU program

```
#include <errno.h>
#include <stdio.h>
#include <stdlib.h>
#include <libspe2.h>

extern spe_program_handle_t hello_spu;

int main(void)
{
    void * argp = NULL;
    void * envp = NULL;
    spe_stop_info_t stop_info;
    int rc;

    // Create an SPE context
    speid = spe_context_create(flags, NULL);
    if (speid == NULL) {
        perror("spe_context_create");
        return -2;
    }

    // Load an SPE executable object into the SPE context local store
    if (spe_program_load(speid, &hello_spu)) {
        perror("spe_program_load");
        return -3;
    }

    // Run the SPE context
    rc = spe_context_run(speid, &entry, 0,
                         argp, envp, &stop_info);
    if (rc < 0)
        perror("spe_context_run");

    // Destroy the SPE context
    spe_context_destroy(speid);
    return 0;
}
```

**PPU Makefile**

```
DIRS = spu
PROGRAM_ppu = hello_be1
IMPORTS = spu/hello_spu.a -lspe2 -lpthread
include $(CELL_TOP)/buildutils/make.footer
```
The IBM Full System Simulator – An Overview
Simulator Overview

**Development Environment:**
- Application Source Code
- Programming Tools
  - OpenMP
  - MPI
- Compilers

**Software Stack:**
- Executables
- Runtime and libraries
- System Software: Hypervisor, Linux/PPC or K42

**SystemSim:**
- Simulation of hardware
- BE
- ROM
- Disks
- DMA
- UART
- Caches (L1/L2)
- Int Ctrlr
- Memory
- Bus
- L3

**Real Systems:**
- Linux (Fedora Core 5)
- PowerPC
- Intel x86
- x86-64

**Console Window**

**GUI Windows**

**Traces**
SystemSim Runtime Environment

Startup TCL File (.systemsim.tcl)

```
# Create simulator instance
define dup cell mysim
# Load kernel boot image
mysim load vmlinux ./vmlinux 0x1000000
# Start the GUI
MamboInit::gui
```

1. Tcl/Tk/BLT GUI Scripts
2. tcl/tk/blt/mambo cmds
3. Kernel Boot Image (vmlinux)
4. Disk Image (sysroot_disk)
5. Network Service Daemon

- Console
- ROM Image (rom.bin)
- CPU Model
- Memory
- ROM
- Net Model
- Console
- Disk Model
SystemSim User Interface

- **Graphical interface**
  - Provides a visual display of the state of the simulated system, including the PPE and the eight (or 16) SPEs
  - Includes dialogs to view the contents of the registers, memory, and channels, and other architectural structures
  - Based on Tcl/Tk
  - Layered on top of the command line interface

- **Command line**
  - Uses Tcl (Tool Control Language) as the base command interpreter
  - All the standard Tcl commands are available
  - SystemSim commands to configure and create simulated machines
  - Commands (e.g. mysim) to control a specific simulated machine
Operating-System Modes

- **Linux Mode**
  - Simulator boots a full Linux operating system on the simulated system
  - Applications are launched from the Linux console window and run
  - The simulated operating system handles all the system calls

- **Standalone Mode**
  - The application is loaded directly into the simulated machine without an operating system
  - The simulator traps all system calls made by the application and performs these functions in place of the operating system
  - Some restrictions apply, such as
    - The application must be statically linked with any libraries it needs
    - No virtual memory support is provided
    - Only a subset of system calls are supported
Simulator Structure and Windows

Command Window

systemsim%

GUI Window

Console Window

[user@bringup /]#

Simulated System

Simulator

Base Simulator
Hosting Environment

Base processor

Linux Operating System

IBM Full System Simulator

Cell Simulated Machine

Linux on Simulated Machine

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Interacting with the Simulator

- **Issuing commands to the simulator**
  - in the simulator command window, or using the equivalent actions in the graphical user interface (GUI).
  - To control the simulator itself, configuring it to do such tasks as collect and display performance statistics on particular SPEs, or set breakpoints in code.

- **Issuing commands to the simulated system**
  - in the console window which is a Linux shell of the simulated Linux operating system.
  - The simulated system is the Linux environment on top of the simulated cell, where you run and debug programs.
Starting the Simulator in GUI Interface

- **The simulator is invoked with the systemsim command “systemsim –g”**
  - Note: add /opt/ibm/systemsim-cell/bin to your path

- **Specify the initial run script using –f if configuration is needed**
  - file should be in the current directory or path qualified
  - This configures the simulated machine and prepares it for execution
  - The default is .systemsim.tcl
  - Samples are provided in the simulator run directory
    - Linux mode:
      - /opt/ibm/systemsim-cell/run/cell/linux/systemsim.tcl

- **Other systemsim options**
  - -n : do not open a console window
  - -q : suppress periodic run statistics messages
  - -g : enable the graphical interface

- **Starting the simulator in GUI mode with two Cell BE (SMP configuration)**
  - systemsim –g –f config_smp.tcl

- **Another way to start the simulator**
  - # cd /opt/ibm/systemsim-cell/run/cell/linux
  - ../../../run_gui
SystemSim Cell GUI main panel
Basic Simulator operations
The PPE
The PPE
The SPU
Simulator Modes – fast, simple, and cycle

- The default simulation mode when the simulator starts is “simple”, or functional-only, simulation
  - In this mode, the time / cycles to execute an application is NOT a meaningful indicator of execution time on real hardware

- To get meaningful performance results:
  - Select “Cycle” mode on the GUI
  - Enter “mysim mode cycle” in the command window

- This will make the simulator run slower
  - Depending on the workload, simulation time could increase by 10x to 100x
  - But you can switch between modes as needed, so you can limit this overhead to just the relevant portions of the simulation
How to Exchange Files between Host and Simulator

- **callthru**
  - A command issued from a simulated windows (from the simulator)
  - “backdoor” communication mechanism for the simulated environment to communicate with the host environment
  - Useful for bringing in files to the simulated environment without shutting down and restarting the simulator
  - Example: (binary host → simulator)
    - callthru source /opt/cell_class/Hands-on-30/hello/hello_ppu/hello_ppu > hello_ppu
    - chmod 755 hello_ppu
    - ./hello_ppu
  - Example (result file simulator → host)
    - callthru sink /home/systemsim-cell/results/result_file < cat result_file
    - exporting result files out of the simulated environment for later inspection
Execute Binary

- From the simulated windows, bring executable into the simulator by using the callthru utility, e.g.,
  - callthru source /opt/cell_class/Hands-on-30/hello/hello_ppu/hello_ppu > hello_ppu

- Execute binary
  - chmod 755 hello_ppu
  - ./hello_ppu

Tip!
Copy binary to /tmp/´<exe> on host to shorten the filename
Building three types of the hello world! program
Directory Structure

/opt/cell_class/Hands-on-30/hello

- hello_ppu
- hello_spu
- hello_be1 synchronous spu thread (hello_be1-sync)
  - spu
- hello_be1 asynchronous spu thread (hello_be1-async)
  - spu
Hands-on Exercise

1. Create a directory hello_ppu, write a hello world ppu program and create a Makefile, then compile and execute it as a standalone ppu program

2. Create a directory hello_spu, write a hello world spu program and create a Makefile, then compile and execute it as a standalone spu program

3. Create a directory hello_be1, and write a ppu program that calls an spu program to write hello world in a synchronous manner. Create all ppu and spu makefiles. Compile and execute those programs to demonstrate the basic structure of a simple PPE-SPE software synergy model (PPE-single SPE model)

4. Same as in 3. but with asynchronous thread

5. Producing a simple multi-threaded hello world program
   - See instructions in the next page

Need to compile (use make) and run the executables on the simulator
Hands-on – multi-threaded hello world

To produce a simple program for the CBE, you should follow the steps listed below (this example is included in the SDK in /opt/cell/sdk/src/tutorial/simple).

The project is called simple. For this example, the PPE code will be built in the project directory, instead of a ppu sub-directory.

This program creates SPE threads that output “Hello Cell (#)\n” to the systemsim output window, where # is the spe_id of the SPE thread that issued the print.

1. Create a directory named simple.

2. In directory simple, create a file named Makefile using the following code:

```bash
########################################################################
# Subdirectories
########################################################################
DIRS := spu
########################################################################
# Target
########################################################################
PROGRAM_ppu := simple
########################################################################
# Local Defines
```

...
Hands-on – multi-threaded hello world (cont’d)

IMPORTS := spu/lib_simple_spu.a -lspe2 -lpthread
# imports the embedded simple_spu library
# allows consolidation of spu program into ppe binary
########################################################################
# make.footer
########################################################################
# make.footer is in the top of the SDK
ifdef CELL_TOP
  include $(CELL_TOP)/buildutils/make.footer
else
  include ../../../buildutils/make.footer
endif

3. In directory simple, create a file simple.c using the following code:

#include <stdlib.h>
#include <stdio.h>
#include <errno.h>
#include <libspe2.h>
#include <pthread.h>

#include <stdout.h>
Hands-on – multi-threaded hello world (cont’d)

extern spe_program_handle_t simple_spu;
#define MAX_SPU_THREADS 16
void *ppu_pthread_function(void *arg) {
    spe_context_ptr_t ctx;
    unsigned int entry = SPE_DEFAULT_ENTRY;
    ctx = *((spe_context_ptr_t *)arg);
    if (spe_context_run(ctx,&entry, 0, NULL, NULL, NULL) < 0) {
        perror("Failed running context");
        exit (1);
    }
    pthread_exit(NULL);
}
int main() {
    int i,spu_threads;
    spe_context_ptr_t ctxs[MAX_SPU_THREADS];
    pthread_t threads[MAX_SPU_THREADS];
Hands-on – multi-threaded hello world (cont’d)

/* Determine the number of SPE threads to create */
spu_threads = spe_cpu_info_get(SPE_COUNT_USABLE_SPES, -1);
if (spu_threads > MAX_SPU_THREADS) spu_threads = MAX_SPU_THREADS;

/* Create several SPE-threads to execute 'simple_spu' */
for (i=0; i<spu_threads; i++) {
    /* Create context */
    if ((ctxs[i] = spe_context_create (0, NULL)) == NULL) {
        perror ("Failed creating context");
        exit (1);
    }
    /* Load program into context */
    if (spe_program_load (ctxs[i],&simple_spu)) {
        perror ("Failed loading program");
        exit (1);
    }
    /* Create thread for each SPE context */
    if (pthread_create (&threads[i], NULL,&ppu_pthread_function,&ctxs[i])) {
        perror ("Failed creating thread");
        exit (1);
    }
}
Hands-on – multi-threaded hello world (cont’d)

/* Wait for SPU-thread to complete execution. */
for (i=0; i<spu_threads; i++) {
    if (pthread_join (threads[i], NULL)) {
        perror("Failed pthread_join");
        exit (1);
    }
}

printf("The program has successfully executed.
");
return (0);

4. Create a directory named spu.
Hands-on – multi-threaded hello world (cont’d)

5. In the directory spu, create a file named Makefile using the following code:

```
# Target

PROGRAMS_spu := simple_spu
# created embedded library
LIBRARY_embed := lib_simple_spu.a

# make.footer
# make.footer is in the top of the SDK
ifdef CELL_TOP
include $(CELL_TOP)/buildutils/make.footer
else
include ../../../buildutils/make.footer
endif
```
Hands-on – multi-threaded hello world (cont’d)

6. In the same directory, create a file simple_spu.c using the following code:

```c
#include <stdio.h>

int main(unsigned long long id)
{
    /* The first parameter of an spu program will always be the spe_id of the spe
    * thread that issued it.
    */

    printf("Hello Cell (0x%llx)\n", id);
    return 0;
}
```

7. Compile the program by entering the following command at the command line while in the simple directory:

```bash
make
```
Summary

- **Compile and execute different types of cell programs on the simulator**
  - Understand the basic differences between a ppu, spu, and BE program
  - Understand the embedded concept of a cellBE program
  - Understand the build process
  - Understand the contents of different Makefile
  - Understand the basic operations of the simulator
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